

A posteriori error estimates and stopping criteria for a two-phase flow with nonlinear complementarity constraints

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Outline

- 1 Introduction
- 2 Model problem and its discretization
- 3 A posteriori analysis
- 4 Numerical experiments
- 5 Conclusion

Introduction

System of PDEs with nonlinear complementarity constraints:

Find $\mathbf{U} \in \mathbb{R}^n$ such that

$$\begin{aligned} \mathcal{A}(\mathbf{U}) &= 0 \\ \mathcal{K}(\mathbf{U}) &\geq 0, \quad \mathcal{G}(\mathbf{U}) \geq 0, \quad \mathcal{K}(\mathbf{U})^T \mathcal{G}(\mathbf{U}) = 0. \end{aligned}$$

Motivation

- Treat nonlinearities on the constraints with the semi-smoothness theory
- Derive a posteriori error estimates at each semismooth step
- Formulate adaptive stopping criteria **to save computational time**

Application

▶▶▶ Compositional two-phase flow with phase transition in porous media.

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Compositional two-phase flow with phase transition

$$\begin{cases} \partial_t l_w + \nabla \cdot (\rho_w^l \mathbf{q}_l + \mathbf{J}_w^l) = Q_w, \\ \partial_t l_h + \nabla \cdot (\rho_h^l \mathbf{q}_l + \rho_h^g \mathbf{q}_g + \mathbf{J}_h^l) = Q_h, \\ \mathbf{1} - \mathbf{S}_l \geq 0, \quad HP_g - \beta_1 \chi_h^1 \geq 0, \quad (\mathbf{1} - \mathbf{S}_l)^T (HP_g - \beta_1 \chi_h^1) = 0 \end{cases}$$

Unknowns: S_l, P_1, χ_h^1

Darcy's law:

Amount of components:

$$l_w = \phi \rho_w^l S_l + \phi \rho_w^g S_g$$

$$l_h = \phi \rho_h^l S_l + \phi \rho_h^g S_g$$

$$\mathbf{q}_l = -\underline{\mathbf{K}} \frac{k_{rl}(S_l)}{\mu_l} [\nabla P_1 - [\rho_w^l + \rho_h^l] g \nabla z]$$

$$\mathbf{q}_g = -\underline{\mathbf{K}} \frac{k_{rg}(S_g)}{\mu_g} [\nabla P_g - [\rho_h^l + \rho_h^g] g \nabla z]$$

Fick flux:

$$\mathbf{J}_h^l = -\phi M^h S_l C_1 D_h^l \nabla \chi_h^1$$

Algebraic closure:

$$S_l + S_g = 1, \quad \chi_h^l + \chi_w^l = 1, \quad \chi_h^g = 1$$

Capillary pressure: $P_g = P_1 + P_c(S_l)$

Assumption

Water incompressible only present in liquid phase and gas slightly compressible

$$\rho_w^l = \text{cst}, \quad \rho_w^g = 0, \quad \rho_g = \beta_g P_g, \quad \rho_h^l = \beta_1 \chi_h^1, \quad \chi_h^g = 1, \quad \chi_w^g = 0$$

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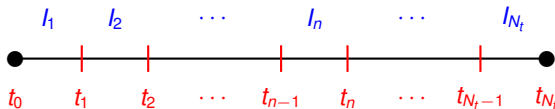
$$\rho_w^l = \text{cst}, \quad \rho_w^g = 0, \quad \rho_g = \beta_g P_g, \quad \rho_h^l = \beta_l \chi_h^1, \quad \chi_h^g = 1, \quad \chi_w^g = 0$$

Discretization by the finite volume method

Numerical solution:

$$\mathbf{U}^n := (\mathbf{U}_K^n)_{K \in \mathcal{T}_h}, \quad \mathbf{U}_K^n := (S_K^n, P_K^n, \chi_K^n) \quad \text{one value per cell}$$

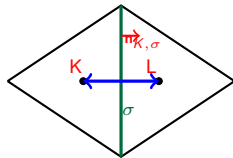
Time discretization: Consider: $t_0 = 0 < t_1 < \dots < t_{N_t} = t_F = N_t \Delta t$ with constant time step Δt .



$$\partial_t^n v_K := \frac{v_K^n - v_K^{n-1}}{\Delta t}.$$

Space discretization: \mathcal{T}_h a superadmissible family of conforming simplicial meshes (Ciarlet) of the space domain Ω .

$$(\nabla v \cdot \mathbf{n}_{K,\sigma}, 1)_\sigma := |\sigma| \frac{v_L - v_K}{d_{KL}} \quad \sigma \in \mathcal{E}_K^{\text{int}},$$



Discretization of water equation

$$\mathbf{S}_{w,K}^n(\mathbf{U}^n) = \partial_t^n l_{w,K} + \sum_{\sigma \in \mathcal{E}_K^{\text{int}}} F_{w,K,\sigma}(\mathbf{U}^n) - Q_{w,K}^n = 0,$$

Total flux

$$F_{w,K,\sigma}(\mathbf{U}^n) = (\mathfrak{M}^l)_\sigma^n (\psi^l)_\sigma^n + (j_w^l)_\sigma^n \quad \sigma \in \mathcal{E}_K^{\text{int}}$$

Discretization of hydrogen equation

$$\mathbf{S}_{h,K}^n(\mathbf{U}^n) = |K| \partial_t^n h_{h,K} + \sum_{\sigma \in \mathcal{E}_K^{\text{int}}} F_{h,K,\sigma}(\mathbf{U}^n) - Q_{h,K}^n = 0,$$

Total flux

$$F_{h,K,\sigma}(\mathbf{U}^n) = \chi_K^n (\mathfrak{M}^l)_\sigma^n (\psi^l)_\sigma^n + (\psi^g)_\sigma^n (\mathfrak{M}^g)_\sigma^n (\rho_g^*)_\sigma^n + (j_h^l)_\sigma^n, \quad \sigma \in \mathcal{E}_K^{\text{int}}$$

- \mathfrak{M}^l : mobility of liquid phase
- \mathfrak{M}^g : mobility of gas phase
- ψ^l : potential of liquid phase
- ψ^g : potential of gas phase

- j_h^l : discrete Fick term
- $Q_{w,K}^n, Q_{h,K}^n$: source term constant in space and time

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Discrete complementarity problem

To reformulate the discrete constraints:

Definition (C-function)

$$\forall (\mathbf{a}, \mathbf{b}) \in \mathbb{R}^n \times \mathbb{R}^n, f(\mathbf{a}, \mathbf{b}) = 0 \iff \mathbf{a} \geq 0, \mathbf{b} \geq 0, \mathbf{a}^T \mathbf{b} = 0$$

min-function: $\min(\mathbf{a}, \mathbf{b}) = 0 \iff \mathbf{a} \geq 0, \mathbf{b} \geq 0, \mathbf{a}^T \mathbf{b} = 0.$

Application: complementarity constraints for the two-phase model

$$1 - S_K^n \geq 0, H(P_K^n + P_c(S_K^n)) - \beta_1 \chi_K^n \geq 0, (1 - S_K^n)^T (H(P_K^n + P_c(S_K^n)) - \beta_1 \chi_K^n) = 0$$



$$\min(1 - S_K^n, H(P_K^n + P_c(S_K^n)) - \beta_1 \chi_K^n) = 0$$

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Bibliography

Global overview



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Weak solution

$$X = L^2((0, t_F); H^1(\Omega)), \quad Y = H^1((0, t_F); L^2(\Omega)), \quad Z = \{v \in L^2((0, t_F); L^2(\Omega)), v \geq 0\}$$

Assumption (Weak formulation)

$$P_l, P_g, \chi_h^1 \in X, \quad S_l, S_g, l_w, l_h \in Y \quad \Phi_w, \Phi_h \in [L^2((0, t_F); \mathbf{H}(\operatorname{div}, \Omega))]^d$$

$$\int_0^{t_F} (\partial_t l_c, \varphi)_\Omega(t) dt - (\Phi_c, \nabla \varphi)_\Omega(t) dt - (Q_c, \varphi)_\Omega(t) dt = 0 \quad \forall \varphi \in X, \quad c = w, h$$

$$\int_0^{t_F} (\lambda - (1 - S_l), HP_g - \beta_l \chi_h^1)_\Omega(t) dt \geq 0 \quad \forall \lambda \in Z, \quad 1 - S_l \in Z, \quad c = w, h$$

The initial condition, as well as the algebraic closure hold.

$$\|\varphi\|_X = \left\{ \sum_{n=1}^{N_t} \int_{I_n} \sum_{K \in \mathcal{T}_h} \|\varphi\|_{X,K}^2 dt \right\}^{\frac{1}{2}}, \quad \|\varphi\|_{X,K}^2 = \varepsilon h_K^{-2} \|\varphi\|_K^2 + \|\nabla \varphi\|_K^2.$$

Define continuous and piecewise \mathbb{P}_1 in time and discontinuous in space functions:

$$\underbrace{l_{c,h\tau}(\cdot, t^n) = l_{c,h}^n}_{\in \mathbb{P}_0}, \quad \underbrace{S_{h\tau}(\cdot, t^n) = S_h^n}_{\in \mathbb{P}_0}, \quad \underbrace{P_{h\tau}(\cdot, t^n) = P_h^n}_{\in \mathbb{P}_2}, \quad \underbrace{\chi_{h\tau}(\cdot, t^n) = \chi_h^n}_{\in \mathbb{P}_2}$$

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Error measure

Dual norm of the residual for the components

$$\|\mathcal{R}_c(\mathbf{S}_{h\tau}, P_{h\tau}, \chi_{h\tau})\|_{X'} = \sup_{\varphi \in X, \|\varphi\|_X=1} \left| \int_0^{t_F} (Q_c - \partial_t l_{c,h\tau}, \varphi)_\Omega(t) + (\Phi_{c,h\tau}, \nabla \varphi)_\Omega(t) dt \right|.$$

Residual for the constraints

$$\mathcal{R}_e(\mathbf{S}_{h\tau}, P_{h\tau}, \chi_{h\tau}) = \int_0^{t_F} (1 - \mathbf{S}_{h\tau}, H[P_{h\tau} + P_c(\mathbf{S}_{h\tau})] - \beta_1 \chi_{h\tau})_\Omega(t) dt.$$

Error measure for the nonconformity of the pressure

$$\mathcal{N}_p = \inf_{\delta_p \in X} \left\{ \sum_{c \in \mathcal{C}_p} \int_0^{t_F} \|\mu_p^{-1} k_{rp}(S_p) \rho_c^p \underline{\mathbf{K}} \nabla (P_{h\tau} - \delta_p)(t)\|^2 dt \right\}^{\frac{1}{2}},$$

Error measure for nonconformity of the mole fraction

$$\mathcal{N}_\chi := \inf_{\theta \in X} \left\{ \int_0^{t_F} \|-M^h \mathbf{S}_{h\tau} (\rho_w^1 / M^w + \beta_1 / M^h \chi_{h\tau}) D_h^1 \nabla (\chi_{h\tau} - \theta)(t)\|^2 dt \right\}^{\frac{1}{2}},$$

Definition (Error measure)

$$\mathcal{N} = \left\{ \sum_{c \in \mathcal{C}} \|\mathcal{R}_c(\mathbf{S}_{h\tau}, P_{h\tau}, \chi_{h\tau})\|_{X'}^2 \right\}^{\frac{1}{2}} + \left\{ \sum_{p \in \mathcal{P}} \mathcal{N}_p^2 + \mathcal{N}_\chi^2 \right\}^{\frac{1}{2}} + \mathcal{R}_e(\mathbf{S}_{h\tau}, P_{h\tau}, \chi_{h\tau})$$

Raviart Thomas spaces

Definition

The lowest-order Raviart–Thomas space is defined by

$$\mathbf{RT}_0(\Omega) = \{ \mathbf{w}_h \in \mathbf{H}(\operatorname{div}, \Omega), \mathbf{w}_h|_K \in \mathbf{RT}_0(K) \forall K \in \mathcal{T}_h \}$$

$$\mathbf{RT}_0(K) = [\mathbb{P}_0(K)]^2 + \vec{\mathbf{x}} \cdot \mathbb{P}_0(K)$$

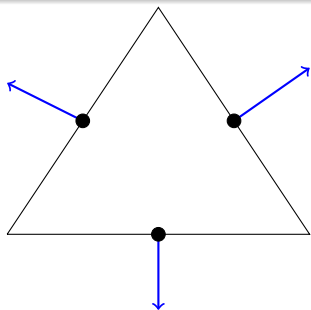


Figure: \mathbf{RT}_0 space.

Degrees of freedom:

$$\mathbf{v}_j = (\mathbf{v} \cdot \mathbf{n}_{e_j}, 1)_{e_j}, \quad e_j \in \partial K, \quad j = \{1, 2, 3\}.$$

Phase pressure reconstruction

$P_K^{n,k,i}$ constant $\Rightarrow \nabla P_K^{n,k,i} = 0$.

Define $\xi_{1,h}^{n,k,i} \in \mathbf{RT}_0(K)$

$$\left(\xi_{1,h}^{n,k,i} \cdot \mathbf{n}_K, 1 \right)_\sigma = -|\sigma| \frac{P_L^{n,k,i} - P_K^{n,k,i}}{d_{KL}}$$

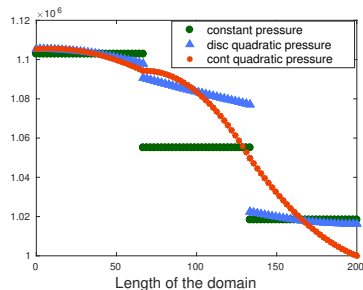
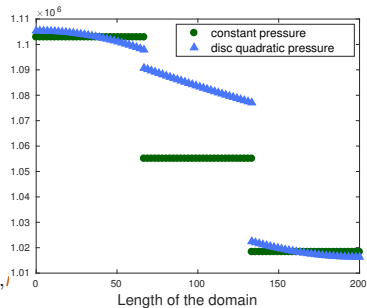
The **discontinuous** \mathbb{P}_2 liquid phase pressure $P_h^{n,k,i}$ satisfy

$$\left(-\nabla P_h^{n,k,i} \right)|_K = \left(\xi_{1,h}^{n,k,i} \right)_K, \quad \left(P_h^{n,k,i}, 1 \right)_K = |K| P_K^{n,k,i}$$

The Oswald interpolation operator

defines continuous \mathbb{P}_2 functions:

- $I_{\text{os}}(P_h^{n,k,i}) \in \mathbb{P}_2 \cap H_0^1(\Omega)$
- $I_{\text{os}}(\widehat{P}_h^{n,k,i}) \in \mathbb{P}_2 \cap H_0^1(\Omega)$



Inexact semismooth Newton method

The finite volume scheme provides

$$|K| \partial_t^n l_{c,K} + \sum_{\sigma \in \mathcal{E}_K} F_{c,K,\sigma}(\mathbf{U}^n) = |K| Q_{h,K}^n,$$

Inexact semismooth linearization

$$\frac{|K|}{\Delta t} \left[l_{c,K}(\mathbf{U}^{n,k-1}) - l_{c,K}^{n-1} + \mathcal{L}_{c,K}^{n,k,i} \right] + \sum_{\sigma \in \mathcal{E}_K^{\text{int}}} F_{c,K,\sigma}^{n,k,i} - |K| Q_{c,K}^n + \mathbf{R}_{c,K}^{n,k,i} = 0$$

Linear perturbation in the accumulation

$$\mathcal{L}_{c,K}^{n,k,i} = \sum_{K' \in \mathcal{T}_h} \frac{|K|}{\Delta t} \frac{\partial l_{c,K}^n}{\partial \mathbf{U}_{K'}^n}(\mathbf{U}_{K'}^{n,k-1}) \left[\mathbf{U}_{K'}^{n,k,i} - \mathbf{U}_{K'}^{n,k-1} \right],$$

Linearized component flux

$$F_{c,K,\sigma}^{n,k,i} = \sum_{K' \in \mathcal{T}_h} \frac{\partial F_{c,K,\sigma}}{\partial \mathbf{U}_{K'}^n}(\mathbf{U}^{n,k-1}) \left[\mathbf{U}_{K'}^{n,k,i} - \mathbf{U}_{K'}^{n,k-1} \right] + F_{c,K,\sigma}(\mathbf{U}^{n,k-1}).$$

Component flux reconstructions

Discretization flux reconstruction:

$$\left(\Theta_{c,h,\text{disc}}^{n,k,i} \cdot \mathbf{n}_K, \mathbf{1} \right)_\sigma = F_{c,K,\sigma}(\mathbf{U}^{n,k,i}) \quad \forall K \in \mathcal{T}_h$$

Linearization flux reconstruction:

$$\left(\Theta_{c,h,\text{lin}}^{n,k,i} \cdot \mathbf{n}_K, \mathbf{1} \right)_\sigma = F_{c,K,\sigma}^{n,k,i} - F_{c,K,\sigma}(\mathbf{U}^{n,k,i}) \quad \forall K \in \mathcal{T}_h,$$

Algebraic flux reconstruction:

$$\left(\Theta_{c,h,\text{alg}}^{n,k,i} \cdot \mathbf{n}_K, \mathbf{1} \right)_{\partial K} = -\mathbf{R}_{c,K}^{n,k,i} \quad \forall K \in \mathcal{T}_h$$

Total flux reconstruction:

$$\Theta_{c,h}^{n,k,i} = \Theta_{c,h,\text{disc}}^{n,k,i} + \Theta_{c,h,\text{lin}}^{n,k,i} + \Theta_{c,h,\text{alg}}^{n,k,i}$$

Proposition (Equilibration property)

$$\left(Q_{c,K}^n - \frac{l_{c,K}(\mathbf{U}^{n,k-1}) - l_{c,K}^{n-1} + \mathcal{L}_{c,K}^{n,k,i}}{\tau_n} - \nabla \cdot \Theta_{c,h}^{n,k,i}, \mathbf{1} \right)_K = 0$$

Error estimators

$$\left. \begin{aligned}
 \eta_{R,K,c}^{n,k,i} &= \min \left\{ C_{PW}, \varepsilon^{-\frac{1}{2}} \right\} h_K \left\| Q_{c,h}^n - \frac{l_{c,K}(\mathbf{U}^{n,k-1}) - l_{c,K}^{n-1} + \mathcal{L}_{c,K}^{n,k,i}}{\tau_n} - \nabla \cdot \Theta_{c,h}^{n,k,i} \right\|_K \\
 \eta_{F,K,c}^{n,k,i}(t) &= \left\| \Theta_{c,h}^{n,k,i} - \Phi_{c,h\tau}^{n,k,i}(t) \right\|_K \\
 \eta_{NC,K,\rho,c}^{n,k,i}(t) &= \left\| \frac{k_{r1}(S_1)}{\mu_1} \rho_c^p \underline{\mathbf{K}} \nabla (P_{h\tau,\rho}^{n,k,i} - I_{os}(P_{h,\rho}^{n,k,i}))(t) \right\|_K \quad t \in I_n, \\
 \eta_{P,K, \text{pos}}^{n,k,i}(t) &= \left(\left\{ 1 - S_{h\tau}^{n,k,i} \right\}^+(t), \left\{ H \left[P_{h\tau}^{n,k,i} + P_c \left(S_{h\tau}^{n,k,i} \right) \right] - \beta_1 \chi_{h\tau}^{n,k,i} \right\}^+(t) \right)_K
 \end{aligned} \right\} \eta_{\text{disc}}^{n,k,i}$$

$$\left. \begin{aligned}
 \eta_{NA,K,c}^{n,k,i} &= \varepsilon^{-\frac{1}{2}} h_K (\tau_n)^{-1} \left\| l_{c,K}(\mathbf{U}^{n,k,i}) - l_{c,K}(\mathbf{U}^{n,k-1}) - \mathcal{L}_{c,K}^{n,k,i} \right\|_K \\
 \eta_{P,K,\text{neg}}^{n,k,i}(t) &= \left(\left\{ 1 - S_{h\tau}^{n,k,i} \right\}^-(t), \left\{ H \left[P_{h\tau}^{n,k,i} + P_c \left(S_{h\tau}^{n,k,i} \right) \right] - \beta_1 \chi_{h\tau}^{n,k,i} \right\}^-(t) \right)_K
 \end{aligned} \right\} \eta_{\text{lin}}^{n,k,i}$$

$$\eta_{\text{alg},K,c}^{n,k,i} = \left\| \Theta_{c,h,\text{alg}}^{n,k,i} \right\|_K \rightarrow \eta_{\text{alg}}^{n,k,i}$$

Theorem

$$\mathcal{N}^n \leq \eta_{\text{disc}}^{n,k,i} + \eta_{\text{lin}}^{n,k,i} + \eta_{\text{alg}}^{n,k,i}$$

Error estimators

$$\left. \begin{aligned}
 \eta_{R,K,c}^{n,k,i} &= \min \left\{ C_{PW}, \varepsilon^{-\frac{1}{2}} \right\} h_K \left\| Q_{c,h}^n - \frac{l_{c,K}(\mathbf{U}^{n,k-1}) - l_{c,K}^{n-1} + \mathcal{L}_{c,K}^{n,k,i}}{\tau_n} - \nabla \cdot \Theta_{c,h}^{n,k,i} \right\|_K \\
 \eta_{F,K,c}^{n,k,i}(t) &= \left\| \Theta_{c,h}^{n,k,i} - \Phi_{c,h\tau}^{n,k,i}(t) \right\|_K \\
 \eta_{NC,K,\rho,c}^{n,k,i}(t) &= \left\| \frac{k_1(S_1)}{\mu_1} \rho_c^p \underline{\mathbf{K}} \nabla (P_{h\tau,\rho}^{n,k,i} - I_{os}(P_{h,\rho}^{n,k,i}))(t) \right\|_K \quad t \in I_n, \\
 \eta_{P,K, \text{pos}}^{n,k,i}(t) &= \left(\left\{ 1 - S_{h\tau}^{n,k,i} \right\}^+(t), \left\{ H \left[P_{h\tau}^{n,k,i} + P_c \left(S_{h\tau}^{n,k,i} \right) \right] - \beta_1 \chi_{h\tau}^{n,k,i} \right\}^+(t) \right)_K \\
 \eta_{NA,K,c}^{n,k,i} &= \varepsilon^{-\frac{1}{2}} h_K (\tau_n)^{-1} \left\| l_{c,K}(\mathbf{U}^{n,k,i}) - l_{c,K}(\mathbf{U}^{n,k-1}) - \mathcal{L}_{c,K}^{n,k,i} \right\|_K \\
 \eta_{P,K, \text{neg}}^{n,k,i}(t) &= \left(\left\{ 1 - S_{h\tau}^{n,k,i} \right\}^-(t), \left\{ H \left[P_{h\tau}^{n,k,i} + P_c \left(S_{h\tau}^{n,k,i} \right) \right] - \beta_1 \chi_{h\tau}^{n,k,i} \right\}^-(t) \right)_K
 \end{aligned} \right\} \eta_{\text{disc}}^{n,k,i}$$

$$\eta_{\text{alg},K,c}^{n,k,i} = \left\| \Theta_{c,h,\text{alg}}^{n,k,i} \right\|_K \rightarrow \eta_{\text{alg}}^{n,k,i}$$

Theorem

$$\mathcal{N}^n \leq \eta_{\text{disc}}^{n,k,i} + \eta_{\text{lin}}^{n,k,i} + \eta_{\text{alg}}^{n,k,i}$$

Error estimators

$$\left. \begin{aligned}
 \eta_{R,K,c}^{n,k,i} &= \min \left\{ C_{PW}, \varepsilon^{-\frac{1}{2}} \right\} h_K \left\| Q_{c,h}^n - \frac{l_{c,K}(\mathbf{U}^{n,k-1}) - l_{c,K}^{n-1} + \mathcal{L}_{c,K}^{n,k,i}}{\tau_n} - \nabla \cdot \Theta_{c,h}^{n,k,i} \right\|_K \\
 \eta_{F,K,c}^{n,k,i}(t) &= \left\| \Theta_{c,h}^{n,k,i} - \Phi_{c,h\tau}^{n,k,i}(t) \right\|_K \\
 \eta_{NC,K,\rho,c}^{n,k,i}(t) &= \left\| \frac{k_1(S_1)}{\mu_1} \rho_c^p \underline{\mathbf{K}} \nabla (P_{h\tau,\rho}^{n,k,i} - l_{os}(P_{h,\rho}^{n,k,i}))(t) \right\|_K \quad t \in I_n, \\
 \eta_{P,K,\text{pos}}^{n,k,i}(t) &= \left(\left\{ 1 - S_{h\tau}^{n,k,i} \right\}^+(t), \left\{ H \left[P_{h\tau}^{n,k,i} + P_c \left(S_{h\tau}^{n,k,i} \right) \right] - \beta_1 \chi_{h\tau}^{n,k,i} \right\}^+(t) \right)_K \\
 \eta_{NA,K,c}^{n,k,i} &= \varepsilon^{-\frac{1}{2}} h_K (\tau_n)^{-1} \left\| l_{c,K}(\mathbf{U}^{n,k,i}) - l_{c,K}(\mathbf{U}^{n,k-1}) - \mathcal{L}_{c,K}^{n,k,i} \right\|_K \\
 \eta_{P,K,\text{neg}}^{n,k,i}(t) &= \left(\left\{ 1 - S_{h\tau}^{n,k,i} \right\}^-(t), \left\{ H \left[P_{h\tau}^{n,k,i} + P_c \left(S_{h\tau}^{n,k,i} \right) \right] - \beta_1 \chi_{h\tau}^{n,k,i} \right\}^-(t) \right)_K
 \end{aligned} \right\} \eta_{\text{disc}}^{n,k,i}$$

$$\left. \begin{aligned}
 \eta_{\text{alg},K,c}^{n,k,i} &= \left\| \Theta_{c,h,\text{alg}}^{n,k,i} \right\|_K \rightarrow \eta_{\text{alg}}^{n,k,i}
 \end{aligned} \right\} \eta_{\text{lin}}^{n,k,i}$$

Theorem

$$\mathcal{N}^n \leq \eta_{\text{disc}}^{n,k,i} + \eta_{\text{lin}}^{n,k,i} + \eta_{\text{alg}}^{n,k,i}$$

Adaptivity

Algorithm 1 Adaptive inexact semismooth Newton algorithm

Initialization: Choose an initial vector $\mathbf{U}^{n,0} \in \mathcal{M}_{3N_h,1}(\mathbb{R})$, ($k = 0$)

Do

$k = k + 1$

Compute $\mathbb{A}^{n,k-1} \in \mathcal{M}_{3N_h,3N_h}(\mathbb{R})$, $\mathbf{B}^{n,k-1} \in \mathcal{M}_{3N_h,1}(\mathbb{R})$

Consider $\mathbb{A}^{n,k-1} \mathbf{U}^{n,k} = \mathbf{B}^{n,k-1}$

Initialization for the linear solver: Define $\mathbf{U}^{n,k,0} = \mathbf{U}^{n,k-1}$, ($i = 0$)

Do

$i = i + 1$

Compute Residual: $\mathbf{R}^{n,k,i} = \mathbf{B}^{n,k-1} - \mathbb{A}^{n,k-1} \mathbf{U}^{n,k,i}$

Compute estimators

While $\eta_{\text{alg}}^{n,k,i} \geq \gamma_{\text{alg}} \max \left\{ \eta_{\text{disc}}^{n,k,i}, \eta_{\text{lin}}^{n,k,i} \right\}$

While $\eta_{\text{lin}}^{n,k,i} \geq \gamma_{\text{lin}} \eta_{\text{disc}}^{n,k,i}$

End




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- 1 Introduction
- 2 Model problem and its discretization
- 3 A posteriori analysis
- 4 Numerical experiments**
- 5 Conclusion

Numerical experiments

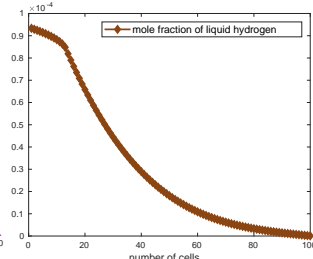
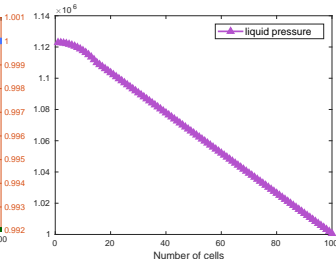
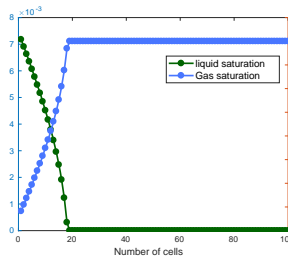
Ω : one-dimensional core with length $L = 200m$. We consider the **semismooth Newton-min solver** and assume that the algebraic solver has converged.

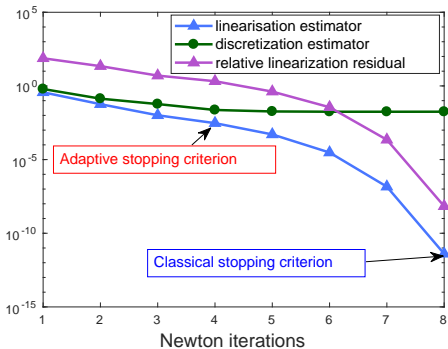
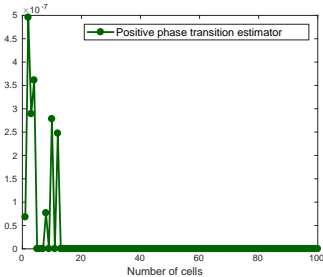
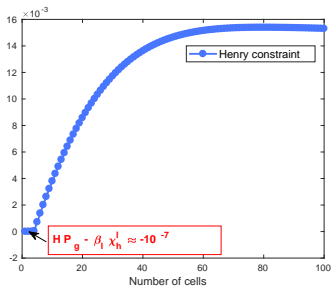
Gas injection  liquid

Van Genuchten–Mualem model:

$$P_c(S_l) = P_r \left(S_{le}^{-\frac{1}{m}} - 1 \right)^{\frac{1}{n}}$$

$$k_{rl}(S_l) = \sqrt{S_{le}} \left(1 - \left(1 - S_{le}^{\frac{1}{m}} \right)^m \right)^2, \quad k_{rg}(S_l) = \sqrt{1 - S_{le}} \left(1 - S_{le}^{\frac{1}{m}} \right)^{2m}$$





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Conclusion

- We devised an a posteriori error estimate between the exact and approximate solution for a wide class of semi-smooth Newton methods.
- This estimate distinguishes the error components \Rightarrow adaptive stopping criteria.
- The adaptive semismooth Newton method requires less iterations.

Ongoing work:

- Devise adaptive stopping criteria for algebraic solver
- Devise space-time adaptivity

Thank you for your attention!